

A1

1

$\left\{ \overbrace{\begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}}^{x_1}, \overbrace{\begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}}^{x_2}, \overbrace{\begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}}^{x_3} \right\}$ on $\mathbb{R}^3$:n kanta,

jos vektorit ovat lineaarisesti riippumattomat. Tällöin seuraavalla yhtälöryhmällä on vain triviaaliratkaisu.

$$\overbrace{\begin{pmatrix} 0 & 1 & 2 \\ 1 & 3 & 1 \\ 2 & 1 & 0 \end{pmatrix}}^{=A} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = 0$$

$$\iff \det(A) \neq 0$$

$$\det(A) = - \begin{vmatrix} 1 & 1 \\ 2 & 0 \end{vmatrix} + 2 \begin{vmatrix} 1 & 3 \\ 2 & 1 \end{vmatrix} = 2 - 10 = -8 \quad \square$$

Gram-Schmidt:

$$e_1 = \frac{x_1}{\|x_1\|} = \frac{x_1}{\sqrt{1^2+2^2}} = \begin{pmatrix} 0 \\ \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{pmatrix}$$

$$\begin{aligned} \tilde{e}_2 &= x_2 - (x_2^T e_1) e_1 = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} - \overbrace{\left(\frac{3}{\sqrt{5}} + \frac{2}{\sqrt{5}} \right)}^{=\sqrt{5}} \begin{pmatrix} 0 \\ \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{pmatrix} \\ &= \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \end{aligned}$$

$$e_2 = \frac{\tilde{e}_2}{\|\tilde{e}_2\|} = \frac{\tilde{e}_2}{\sqrt{1^2+2^2+1^2}} = \begin{pmatrix} \frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{pmatrix}$$

$$\begin{aligned} \tilde{e}_3 &= x_3 - (x_3^T e_1) e_1 - (x_3^T e_2) e_2 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{\sqrt{5}} \begin{pmatrix} 0 \\ \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{pmatrix} - \frac{4}{\sqrt{6}} \begin{pmatrix} \frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ \frac{1}{5} \\ \frac{2}{5} \end{pmatrix} - \begin{pmatrix} \frac{4}{3} \\ \frac{8}{15} \\ -\frac{4}{15} \end{pmatrix} = \begin{pmatrix} \frac{4}{3} \\ \frac{3}{5} \\ +\frac{4}{15} \end{pmatrix} \end{aligned}$$

$$e_3 = \frac{\tilde{e}_3}{\|\tilde{e}_3\|} = \frac{\tilde{e}_3}{\sqrt{\left(\frac{4}{3}\right)^2 + \left(\frac{3}{5}\right)^2 + \left(\frac{4}{15}\right)^2}} = \frac{15}{\sqrt{480}} \begin{pmatrix} \frac{4}{3} \\ \frac{3}{5} \\ -\frac{4}{15} \end{pmatrix} = \frac{1}{\sqrt{480}} \begin{pmatrix} 20 \\ -8 \\ -4 \end{pmatrix}$$

e_1, e_2 ja e_3 muodostavat ortonormaalin kannan

A2

2

Matriisinormin määritelmä:

$$\|A\|_1 := \max_{\|x\|_1=1} \|Ax\|_1 \quad \text{eli} \quad \|x\|_1 = \sum_{j=1}^n |x_j| = 1$$

$$\|Ax\|_1 = \sum_{i=1}^n \left| \sum_{j=1}^n a_{ij} x_j \right| \leq \sum_{i=1}^n \sum_{j=1}^n \overbrace{|a_{ij} x_j|}^{= |a_{ij}| \|x_j\|} = \sum_{i=1}^n \sum_{j=1}^n |a_{ij}| |x_j|$$

$$= \sum_{j=1}^n \left(|x_j| \sum_{i=1}^n |a_{ij}| \right) \leq \max_k \sum_{i=1}^n |a_{ik}| \sum_{j=1}^n |x_j| = \max_k \sum_{i=1}^n |a_{ik}|$$

$\nearrow \leq \max_k \sum_{i=1}^n |a_{ik}|$

$\nwarrow$ j:n sarakkeen alkioiden itseisarvojen summa
 $\swarrow$ suurin itseisarvojen sarakesumma

Osoitetaan vielä, että $\|Ax\|_1$ voi saada arvon $\max_k \sum_{i=1}^n |a_{ik}|$

Jos L on indeksi, joka maksimoi itseisarvojen sarakesumman. Eli

$$\sum_{i=1}^n |a_{iL}| = \max_k \sum_{i=1}^n |a_{ik}|$$

Silloin

$$\|Ae^L\|_1 = \sum_{i=1}^n |a_{iL}|$$

$$e^L = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \leftarrow L\text{:s alkio}$$

$$\Rightarrow \|A\|_1 = \max_k \sum_{i=1}^n |a_{ik}|$$

A3) a)

$$A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 0 \\ 1 & 1 & 2 \end{pmatrix}$$

A:n ominaisarvot:

$$\det(A - \lambda I) = (1 - \lambda)(2 - \lambda)^2 \Rightarrow \lambda_1 = 1 \text{ ja } \lambda_2 = \lambda_3 = 2$$

A:n ominaisvektorit:

$$\lambda = 1 \quad \left(\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right) \rightsquigarrow \left(\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \end{array} \right) \Rightarrow V_1 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$$

$$\lambda = 2 \quad \left(\begin{array}{ccc|c} -1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{array} \right) \rightsquigarrow \left(\begin{array}{ccc|c} -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right) \Rightarrow V_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Vain 2 ominaisvektoria $\Rightarrow A$ ei diagonalisoidu.

Ratkaistaan Jordan-muoto:

$$\begin{pmatrix} 1 & 0 & 0 \\ -1 & 2 & 0 \\ 1 & 1 & 2 \end{pmatrix} (V_1 \ V_2 \ \overset{\text{tunteeton}}{W}) = (V_1 \ V_2 \ \overset{\text{tunteeton}}{W}) \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}}_{=J}$$

$$\Rightarrow AW = V_2 + 2W$$

$$(A - 2I)W = V_2$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix} W = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \Rightarrow W = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$X = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix}$$

$$X^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \\ -1 & 1 & 0 \end{pmatrix}$$

$$e^A = X e^J X^{-1}$$

Lasketaan Jordanlohkon eksponentti;

$$e^{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}} = e^{2I + \overbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}^{=N}} = e^{2I} \cdot e^N = e^{2I} (I + N)$$

$$= \begin{pmatrix} e^2 & 0 \\ 0 & e^2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} e^2 & e^2 \\ 0 & e^2 \end{pmatrix}$$

$$e^A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix} \begin{pmatrix} e & 0 & 0 \\ 0 & e^2 & e^2 \\ 0 & 0 & e^2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \\ -1 & 1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} e & 0 & 0 \\ e & 0 & e^2 \\ -2e & e^2 & e^2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 0 & 1 \\ -1 & 1 & 0 \end{pmatrix} = \underline{\underline{\begin{pmatrix} e & 0 & 0 \\ e - e^2 & e^2 & 0 \\ -2e + e^2 & e^2 & e^2 \end{pmatrix}}}$$

HUOM! Jordan-muodon laskemisesta ei edellytetä tällä kurssilla.

A3) b)

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$$A = \begin{pmatrix} 4 & -6 \\ 2 & -3 \end{pmatrix}$$

A:n ominaisarvot:

$$\det(A - \lambda I) = (4 - \lambda)(-3 - \lambda) + 12$$

$$= \lambda^2 - \lambda = \lambda(\lambda - 1) \Rightarrow \lambda_1 = 0 \quad \lambda_2 = 1$$

A:n ominaisvektorit:

$$\bullet \lambda_1 = 0 \quad \begin{pmatrix} 4 & -6 & | & 0 \\ 2 & -3 & | & 0 \end{pmatrix} \hookrightarrow \begin{pmatrix} 2 & -3 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix} \Rightarrow V_1 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$\lambda_2 = 1 \quad \begin{pmatrix} 3 & -6 & | & 0 \\ 2 & -4 & | & 0 \end{pmatrix} \hookrightarrow \begin{pmatrix} 1 & -2 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix} \Rightarrow V_2 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$X = \begin{pmatrix} 3 & 2 \\ 2 & 1 \end{pmatrix} \quad X^{-1} = \frac{1}{-1} \begin{pmatrix} 1 & -2 \\ -2 & 3 \end{pmatrix} = \begin{pmatrix} -1 & 2 \\ 2 & -3 \end{pmatrix}$$

$$\bullet e^A = X e^{\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}} X^{-1} = \begin{pmatrix} 3 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & e \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 2 & -3 \end{pmatrix}$$

$$= \begin{pmatrix} 3 & 2e \\ 2 & e \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 2 & -3 \end{pmatrix} = \underline{\underline{\begin{pmatrix} -3+4e & 6-6e \\ -2+2e & 4-3e \end{pmatrix}}}$$

6

L1 a) Olkoon A ja B ortogonaalisia ja $C=AB$
 $\Rightarrow AA^T=I$ ja $BB^T=I$

$$CC^T = AB(AB)^T = A \underbrace{BB^T}_I A^T = AA^T = I$$

C on siis myös ortogonaalinen. $\square$

b) A ja B ovat alakolmiomatriiseja ja $C=AB$

$$\Rightarrow a_{ij}=0 \text{ jos } i < j$$

$$b_{ij}=0 \text{ jos } i < j$$

Tutkitaan C :n alkioita, jotka ovat diagonaalien yläpuolella. Siis $i < j$

$$c_{ij} = [AB]_{ij} = \sum_{k=1}^n a_{ik} b_{kj} = \sum_{k=1}^{j-1} a_{ik} \underbrace{b_{kj}}_{=0} + \sum_{k=j}^n a_{ik} \underbrace{b_{kj}}_{=0, \text{ koska } k \leq j} = 0$$

C on siis alakolmiomatriisi.

c) Tarkastellaan käänteismatriisin laskemista Gaussin algoritmilla. #=jotain

$$\left(\begin{array}{ccc|ccc} a_{11} & & & 1 & & \\ a_{12} & a_{22} & & & 1 & \\ \vdots & & \ddots & & & \ddots \\ a_{n1} & & & 0 & & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} a_{11} & & & 1 & & \\ 0 & a_{22} & & \# & 1 & \\ \vdots & & \ddots & & & \ddots \\ 0 & \# & & & & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} a_{11} & & & 1 & & \\ 0 & a_{22} & & & 1 & \\ \vdots & & \ddots & & & \ddots \\ 0 & & & \# & & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & & & \# & & \\ 1 & & & \# & & \\ \vdots & & \ddots & & & \ddots \\ 1 & & & \# & & 1 \end{array} \right)$$

A^{-1}

A^{-1} on alakolmiomatriisi.

L2

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Oletetaan, että N diagonalisoituu
 $N = X D_N X^{-1}$

$$\Rightarrow N^2 = \underbrace{X D_N^2 X^{-1}}_{=A}$$

$$D_N = \begin{pmatrix} \lambda_{N1} & 0 \\ 0 & \lambda_{N2} \end{pmatrix}$$

Diagonalisoidaan $A = \begin{pmatrix} 5 & 4 \\ 4 & 5 \end{pmatrix}$

A :n ominaisarvot:

$$\bullet \det(A - \lambda I) = (5 - \lambda)^2 - 4^2 = \lambda^2 - 10\lambda + 9 = (\lambda - 1)(\lambda - 9)$$

$$\Rightarrow \lambda_1 = 1 \text{ ja } \lambda_2 = 9$$

A :n ominaisvektorit:

$$\lambda = 1 \quad \left(\begin{array}{cc|c} 4 & 4 & 0 \\ 4 & 4 & 0 \end{array} \right) \hookrightarrow \left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\lambda = 9 \quad \left(\begin{array}{cc|c} -4 & 4 & 0 \\ 4 & -4 & 0 \end{array} \right) \hookrightarrow \left(\begin{array}{cc|c} -1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\bullet X = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \quad X^{-1} = \frac{1}{1 - (-1)} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 9 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$\Rightarrow \begin{cases} \lambda_{N1}^2 = 1 \\ \lambda_{N2}^2 = 9 \end{cases} \Rightarrow \begin{cases} \lambda_{N1} = \pm 1 \\ \lambda_{N2} = \pm 3 \end{cases} \quad \begin{array}{l} N \text{ ei ole} \\ \text{yksikäsitteinen} \end{array}$$

Lasketaan N arvoilla $\lambda_{N1} = 1$ ja $\lambda_{N2} = 3$

$$N = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$$

L3 Tarkastellaan tulon $A(t)B(t)$ yksittäistä alkioita.

$$\left[\frac{d}{dt}(A(t)B(t)) \right]_{ij} = \frac{d}{dt} \sum_{k=1}^n a_{ik}(t)b_{kj}(t)$$

$$= \sum_{k=1}^n \frac{d}{dt}(a_{ik}(t)b_{kj}(t)) = \sum_{k=1}^n (a'_{ik}(t)b_{kj}(t) + a_{ik}(t)b'_{kj}(t))$$

$$= \underbrace{\sum_{k=1}^n a'_{ik}(t)b_{kj}(t)}_{=[A'(t)B(t)]_{ij}} + \underbrace{\sum_{k=1}^n a_{ik}(t)b'_{kj}(t)}_{=[A(t)B'(t)]_{ij}} = [A'(t)B(t) + A(t)B'(t)]_{ij}$$

$$\Rightarrow \frac{d}{dt}(A(t)B(t)) = A'(t)B(t) + A(t)B'(t)$$

L4 Lause: Similaarisilla matriiseilla on samat ominaisarvot ja ~~vektorit~~. (Kreyszig Ed.8 s.392)

Olkoon λ A :n ominaisarvo ja x A :n ominaisvektori, jolloin $Ax = \lambda x$.

$$(A+I)x = Ax + x = \lambda x + x = (\lambda + 1)x$$

$A+I$:n ominaisarvo

$A+I$:n ominaisarvot ovat $\lambda_i + 1$, joten ne eivät ole samoja kuin A :n ominaisarvot λ_i .

A ja $A+I$ eivät ole similaarisia.

L5

Yhtälön $\dot{y} = Ay$ yleinen ratkaisu⁹
voidaan esittää matriisieksponentin
avulla muodossa:

$$y = e^{tA} x_0, \text{ missä } x_0 = y(0)$$

A:n ominaisarvot:

$$\det(A - \lambda I) = (-2 - \lambda)(-2 - \lambda) + 4$$

$$= \lambda^2 + 4\lambda + 8 \Rightarrow \lambda = \frac{-4 \pm \sqrt{16 - 4 \cdot 8}}{2} = \begin{cases} -2 + 2i \\ -2 - 2i \end{cases}$$

A:n ominaisvektorit:

$$\lambda = -2 + 2i \quad \left(\begin{array}{cc|c} -2i & 2 & 0 \\ -2 & -2i & 0 \end{array} \right) \xrightarrow{\cdot i} \left(\begin{array}{cc|c} -i & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow v_1 = \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$\lambda = -2 - 2i \quad \left(\begin{array}{cc|c} 2i & 2 & 0 \\ -2 & 2i & 0 \end{array} \right) \xrightarrow{\cdot i} \left(\begin{array}{cc|c} i & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow v_2 = \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

$$X = \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \quad X^{-1} = \frac{1}{-2i} \begin{pmatrix} -i & -1 \\ -i & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2}i \\ -\frac{1}{2} & \frac{1}{2}i \end{pmatrix}$$

$$e^{tA} = \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} e^{(-2+2i)t} & 0 \\ 0 & e^{(-2-2i)t} \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2}i \\ \frac{1}{2} & \frac{1}{2}i \end{pmatrix}$$

$$= e^{-2t} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} e^{2it} & 0 \\ 0 & e^{-2it} \end{pmatrix} \begin{pmatrix} \frac{1}{2} & -\frac{1}{2}i \\ \frac{1}{2} & \frac{1}{2}i \end{pmatrix} = e^{-2t} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} \begin{pmatrix} \frac{1}{2}e^{2it} & \frac{1}{2}ie^{2it} \\ \frac{1}{2}e^{-2it} & \frac{1}{2}ie^{-2it} \end{pmatrix}$$

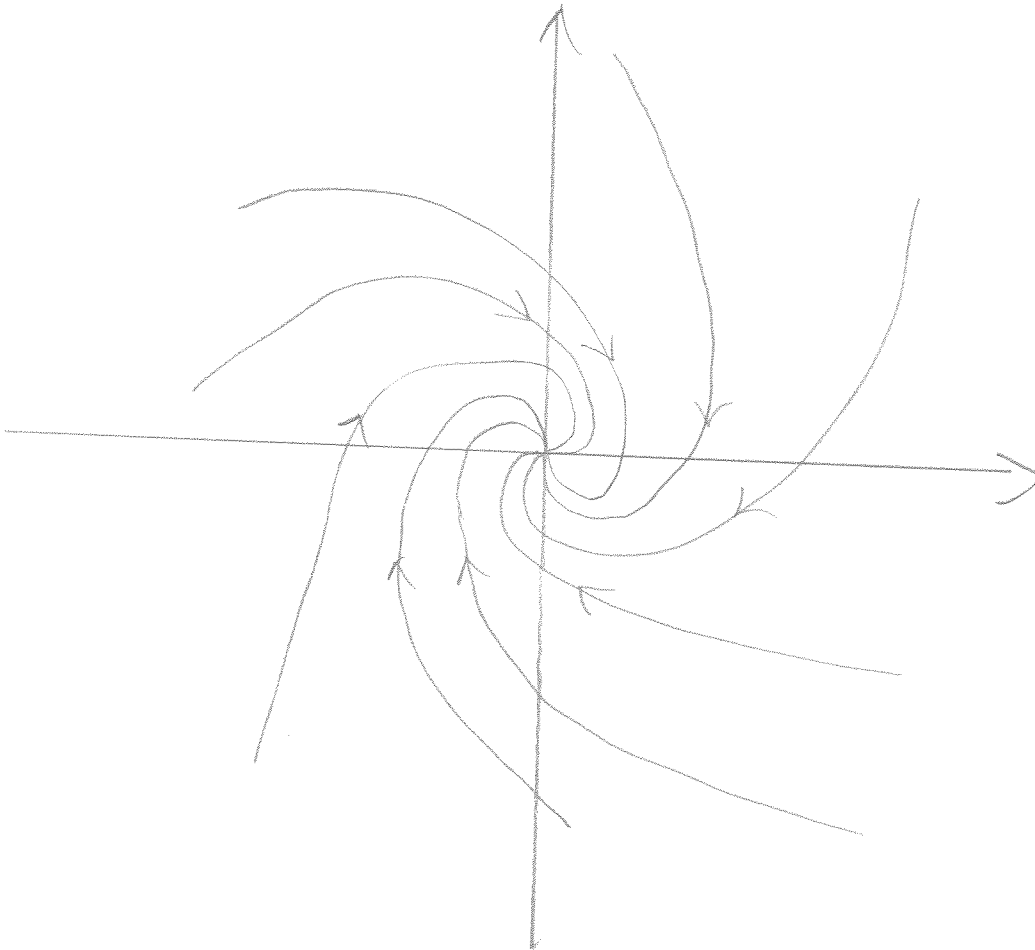
$$= e^{-2t} \begin{pmatrix} \frac{1}{2}(e^{2it} + e^{-2it}) & -\frac{i}{2}(e^{2it} - e^{-2it}) \\ \frac{i}{2}(e^{2it} - e^{-2it}) & \frac{1}{2}(e^{2it} + e^{-2it}) \end{pmatrix}$$

[5]

$$= e^{-2t} \begin{pmatrix} \cos 2t & \sin 2t \\ -\sin 2t & \cos 2t \end{pmatrix}$$

$$Y = \begin{pmatrix} e^{-2t} \cos 2t & e^{-2t} \sin 2t \\ -e^{-2t} \sin 2t & e^{-2t} \cos 2t \end{pmatrix} X_0$$

Koska ominaisarvojen reaaliosa on negatiivinen, origo on stabiili fokus (spiralpointti).



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$$\underline{LG} a) \begin{pmatrix} \dot{y}_1 \\ \dot{y}_2 \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & -4 \\ 1 & -5 \end{pmatrix}}_A \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

A:n ominaisarvot:

$$\det(A - \lambda I) = -\lambda(-5-\lambda) + 4 = \lambda^2 + 5\lambda + 4 \\ = (\lambda + 1)(\lambda + 4) \Rightarrow \lambda_1 = -1 \text{ ja } \lambda_2 = -4$$

A:n ominaisvektorit:

$$\lambda = -1 \quad \left(\begin{array}{cc|c} -1 & -4 & 0 \\ 1 & -4 & 0 \end{array} \right) \hookrightarrow \left(\begin{array}{cc|c} 1 & -4 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow v_1 = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$$

$$\lambda = -4 \quad \left(\begin{array}{cc|c} -4 & -4 & 0 \\ 1 & -1 & 0 \end{array} \right) \Rightarrow v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

yleinen ratkaisu: (Kreyszig Ed. 8 s. 163)

$$y = c_1 \begin{pmatrix} 4 \\ 1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-4t}$$

$$\begin{cases} y_1 = c_1 4e^{-t} + c_2 e^{-4t} \\ y_2 = c_1 e^{-t} + c_2 e^{-4t} \end{cases}$$

L6) b)
$$\begin{pmatrix} \dot{y}_1 \\ \dot{y}_2 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}}_A \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

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A:n ominaisarvot:

$$\det(A - \lambda I) = (1 - \lambda)(1 - \lambda) + 1 = \lambda^2 - 2\lambda + 2$$

$$\lambda = \frac{2 \pm \sqrt{4 - 4 \cdot 2}}{2} = 1 \pm i$$

A:n ominaisvektorit:

$$\lambda = 1 + i \quad \left(\begin{array}{cc|c} -i & -1 & 0 \\ 1 & -i & 0 \end{array} \right) \Rightarrow V_1 = \begin{pmatrix} -1 \\ i \end{pmatrix}$$

$$\lambda = 1 - i \quad \left(\begin{array}{cc|c} i & -1 & 0 \\ 1 & i & 0 \end{array} \right) \Rightarrow V_2 = \begin{pmatrix} 1 \\ i \end{pmatrix}$$

yleinen ratkaisu:

$$\begin{aligned} Y &= C_1 \begin{pmatrix} -1 \\ i \end{pmatrix} e^{(1+i)t} + C_2 \begin{pmatrix} 1 \\ i \end{pmatrix} e^{(1-i)t} \\ &= \begin{pmatrix} -C_1 e^t (\cos t + i \sin t) + C_2 e^t (\cos t - i \sin t) \\ C_1 i e^t (\cos t + i \sin t) + C_2 i e^t (\cos t - i \sin t) \end{pmatrix} \\ &= \begin{pmatrix} (C_2 - C_1) e^t \cos t - i(C_1 + C_2) e^t \sin t \\ i(C_1 + C_2) e^t \cos t + (C_2 - C_1) e^t \sin t \end{pmatrix} \end{aligned}$$

L6 b) Valitaan c_1 ja c_2 s.e.

$$c_2 - c_1 = d_1 \quad \text{ja } d_1, d_2 \in \mathbb{R}$$

$$i(c_1 + c_2) = d_2$$

$$Y = \begin{pmatrix} d_1 e^t \cos t - d_2 e^t \sin t \\ d_2 e^t \cos t + d_1 e^t \sin t \end{pmatrix}$$