Experiments with moduli of quadrilaterals II

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Abstract. The numerical performance of the AFEM method of K. Samuelsson is studied in the computation of moduli of quadrilaterals.

1. Introduction

The moduli of quadrilaterals and rings are some of the fundamental tools in geometric function theory, see [Ahl], [AVV], [Küh], [LV]. The purpose of this paper is to report on our experimental work on the numerical computation of the moduli of quadrilaterals, based on the algorithms and software of [BSV] and motivated by the geometric considerations in [HVV] and [DV]. The methods considered here may be classified into two classes:

- (1) methods based on the definition of the modulus and on conformal mapping of the quadrilateral onto a canonical rectangle,
- (2) methods based on the solution of the Dirichlet-Neumann problem for the Laplace equation.

With the exception of a few special cases both methods lead to extensive numerical computation. For both classes of methods there are several options, see [Gai],[Hen], [Pap]. Among other things, historical remarks are given in [Por].

We study the case of a polygonal quadrilateral and the way its modulus depends on the shape of the quadrilateral. Following the approach of [BSV] our main method is the adaptive finite element method AFEM of Klas Samuelsson and it belongs to class (2). We compare this method to a method of class (1), the Schwarz-Christoffel method of L.N. Trefethen [DrTr] and its MATLAB implementation, the SC Toolbox written by T. Driscoll [Dri]. In the two test cases we have used, the performance of the SC Toolbox was superior to AFEM. On the other hand, the AFEM software applies also to computation of moduli of polygonal ring domains as shown in [BSV]. AFEM also has advantage in the problems where the quadrilateral has large number of vertices. This situation arises when approximating nonpolygonal quadrilaterals (e.g. Example 3.7). We will report our results also in [RV2].

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2. Preliminaries

A Jordan domain D in \mathbb{C} with marked (positively ordered) points $z_1, z_2, z_3, z_4 \in \partial D$ is a quadrilateral and denoted by $(D; z_1, z_2, z_3, z_4)$. We use the canonical map of quadrilateral onto a rectangle (D'; 1+ih, ih, 0, 1), with the vertices corresponding, to define the modulus h of a quadrilateral $(D; z_1, z_2, z_3, z_4)$. The modulus of $(D; z_2, z_3, z_4, z_1)$ is 1/h.

We mainly study the situation where the boundary of D consists of the polygonal line segments through z_1, z_2, z_3, z_4 (always positively oriented). In this case, the modulus is denoted by $QM(D; z_1, z_2, z_3, z_4)$. If the boundary of D consists of straight lines connecting the given boundary points, we omit the domain D and denote the corresponding modulus simply by $QM(z_1, z_2, z_3, z_4)$.

The following problem is known as the *Dirichlet-Neumann problem*. Let D be a region in the complex plane whose boundary ∂D consists of a finite number of regular Jordan curves, so that at every point, except possibly at finitely many points, of the boundary a normal is defined. Let ψ to be a real-valued continuous function defined on ∂D . Let $\partial D = A \cup B$ where A, B both are unions of Jordan arcs. Find a function u satisfying the following conditions:

- 1. u is continuous and differentiable in \overline{D} .
- $2. \ u(t) = \psi(t), \qquad t \in A.$
- 3. If $\partial/\partial n$ denotes differentiation in the direction of the exterior normal, then

$$\frac{\partial}{\partial n}u(t) = \psi(t), \qquad t \in B.$$

One can express the modulus of a quadrilateral $(D; z_1, z_2, z_3, z_4)$ in terms of the solution of the Dirichlet-Neumann problem as follows. Let $\gamma_j, j = 1, 2, 3, 4$ be the arcs of ∂D between (z_1, z_2) , (z_2, z_3) , (z_3, z_4) , (z_4, z_1) , respectively. If u is the (unique) harmonic solution of the Dirichlet-Neumann problem with boundary values of u equal to 0 on γ_2 , equal to 1 on γ_4 and with $\partial u/\partial n = 0$ on $\gamma_1 \cup \gamma_3$, then by [Ahl, p. 65/Thm 4.5]:

(2.1)
$$QM(D; z_1, z_2, z_3, z_4) = \int_D |\nabla u|^2 dm.$$

We also have the following connection to the modulus curve family (see e.g. [AVV, pp. 158–165]): $QM(D; z_1, z_2, z_3, z_4) = M(\Gamma)$, where Γ is the family of all curves joining γ_2 and γ_4 in D.

Another approach is to use the Schwarz-Christoffel formula approximate the conformal mapping f onto the canonical rectangle. This formula gives an expression for a conformal map from the upper half-plane onto the interior of a n-gon. Its vertices are denoted w_1, \ldots, w_n , and $\alpha_1 \pi, \ldots, \alpha_n \pi$ are the corresponding interior angles. The preimages of the vertices (prevertices) are denoted by $z_1 < z_2 < \ldots < z_n$. The Schwarz-Christoffel formula for the map f is

(2.2)
$$f(z) = f(z_0) + c \int_{z_0}^{z} \prod_{j=1}^{n-1} (\zeta - z_j)^{\alpha_j - 1} d\zeta,$$

where c is a (complex) constant. The main difficulty in applying this formula is that the prevertices z_j cannot, in general, be solved analytically. By using a Möbius transformation,

one may choose three of the prevertices arbitarily. The remaining n-3 prevertices are then obtained by solving a system of nonlinear equations. Several methods for solving this problem are discussed in [DrTr], [DrVa], [Bis]. A MATLAB toolbox by T. Driscoll [Dri] contains a collection of algorithms for constructing Schwarz-Christoffel maps and computing the modulus of polygonal quadrilaterals. The toolbox also gives an accuracy estimate for the numerical approximation of the modulus.

3. Experiments

The solutions of the Dirichlet and the Dirichlet-Neumann problems can be approximated by the method of finite elements, see [Hen, pp. 305–314], [Pap]. Hence, this method can also be used to approximate the modulus of quadrilaterals and rings. The Dirichlet-Neumann problem can be numerically solved with AFEM (Adaptive FEM) numerical PDE analysis package by Klas Samuelsson. This software applies, e.g., to compute the modulus (capacity) of a bounded ring whose boundary components are broken lines. Examples and applications for this software are given in [BSV]. In [HVV] a theoretical formula for computing QM(A,B,0,1) was given with its implementation with Mathematica. This lead to a study of the modulus of quadrilateral in [DV]. In the course of the work on [DV], the variation of the modulus was studied when one of the vertices varies and others are kept fixed, and several conjectures were formulated. For these purposes, neither the theoretical algorithm in [HVV] nor the implemented Mathematica program based on it were no longer adequate and we started to look for a robust program to compute QM(A,B,0,1). It seems that the AFEM software of Samuelsson is very efficient for this purpose. As in [RV1] we use the AFEM software of Samuelsson for computations involving moduli of polygonal quadrilaterals.

3.1. Example. Let f(x,y) = QM(x+iy,i,0,1) - 1/QM(y+ix,i,0,1). Then by [Hen, p. 433] we see that $f(x,y) \equiv 0$. Therefore we may use this function as a measure of the accuracy of AFEM software and SC Toolbox.

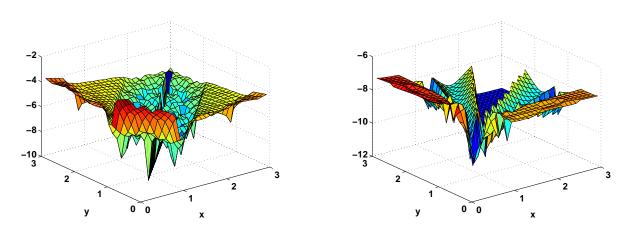


FIGURE 1: Function $\log_{10}(|f(x,y)| + 10^{-10})$ for $x \in (0,3]$, $y \in (0,3]$ with AFEM (left) and SC Toolbox (right).

3.2. Example. We study the function

$$g(t,h) = QM(1 + he^{it}, he^{it}, 0, 1).$$

An analytic expression for this function has been given in [AQVV, 2.3]:

$$(3.3) g(t,h) = \mathcal{K}'(r_{t/\pi})/\mathcal{K}(r_{t/\pi}),$$

where

(3.4)
$$r_a = \mu_a^{-1} \left(\frac{\pi h}{2 \sin(\pi a)} \right)$$
, for $0 < a \le 1/2$,

and the decreasing homeomorphism $\mu_a:(0,1)\to(0,\infty)$ is defined by

(3.5)
$$\mu_a(r) \equiv \frac{\pi}{2\sin(\pi a)} \frac{F(a, 1 - a; 1; 1 - r^2)}{F(a, 1 - a; 1; r^2)}.$$

Here

$$F(a,b;c;z) = {}_{2}F_{1}(a,b;c;z) \equiv \sum_{n=0}^{\infty} \frac{(a,n)(b,n)}{(c,n)} \frac{z^{n}}{n!}, \qquad |z| < 1,$$

is the Gaussian hypergeometric function,

$$(a,n) \equiv a(a+1)(a+2)\dots(a+n-1), \qquad (a,0) = 1 \text{ for } a \neq 0,$$

is the shifted factorial function, and the elliptic integrals $\mathcal{K}(r)$, $\mathcal{K}'(r)$ are defined by

$$\mathcal{K}(r) = \frac{\pi}{2} F(1/2, 1/2; 1; r^2), \qquad \mathcal{K}'(r) = \mathcal{K}(r'), \text{ and } r' = \sqrt{1 - r^2}.$$

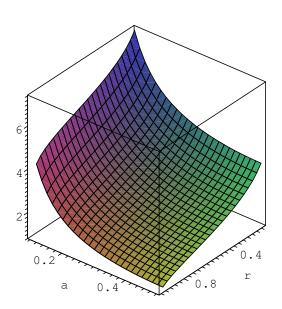


FIGURE 2: Function $\mu_a(r)$.

The function g(t,h) is the modulus of the parallelogram with opposite sides 1 and h, respectively, and we see that there are three cases $h \in (0,1)$, h = 1 and h > 1. In the first case the function is monotone increasing with respect to $t \in (0, \pi/2)$, in the second case the function $g(t,1) \equiv 1$ is constant and in the third case decreasing.

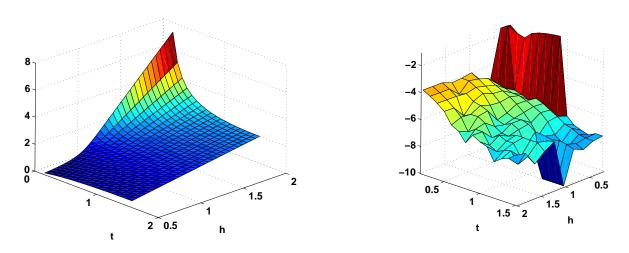


FIGURE 3: Function g(t,h) for $t \in (0,\pi/2)$ and $h \in [1/2,2]$ (left), and error estimate $\log_{10}(|g_{\text{exact}}(t,h) - g_{\text{numer}}(t,h)| + 10^{-10})$ for the function g(t,h) (right).

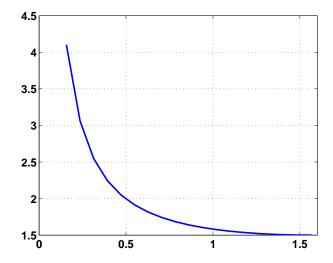


FIGURE 4: Function g(t, 1.5) for $t \in (0, \pi/2)$.

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3.6. Example. The modulus QM(1+i|a-1|,i|b|,0,1) has an analytic expression if |a-1|=h=|b|+1. Bowman [Bow, pp. 103-104] gives a formula for the conformal modulus of the quadrilateral with vertices 1+hi, (h-1)i, 0, and 1 when h>1 as $M(h)\equiv \mathcal{K}(r)/\mathcal{K}(r')$ where

$$r = \left(\frac{t_1 - t_2}{t_1 + t_2}\right)^2$$
, $t_1 = \mu_{1/2}^{-1} \left(\frac{\pi}{2c}\right)$, $t_2 = \mu_{1/2}^{-1} \left(\frac{\pi c}{2}\right)$, $c = 2h - 1$.

Therefore, the quadrilateral can be conformally mapped onto the rectangle 1+iM(h), iM(h), 0, 1, with the vertices corresponding to each other. It is clear that $h-1 \leq M(h) \leq h$. The formula

$$M(h) = h + c + O(e^{-\pi h}), \qquad c = -1/2 - \log 2/\pi \approx -0.720636,$$

is given in [PS]. As fas as we know there is neither an explicit nor asymptotic formula for the case when the angle $\pi/4$ of the trapezoid is equal to $\alpha \in (0, \pi/2)$. We compute the modulus QM(ih, i(h-1), 0, 1) by using Bowman's formula, AFEM and Schwarz-Christoffel Toolbox.

h	AFEM	\mathbf{SC}	Accuracy/SC	Bowman	Error/AFEM	Error/SC
1.1	0.3403159	0.3403135	1.787e - 08	0.3403135	2.41655e - 06	1.57002e - 09
1.2	0.4614938	0.4614926	1.734e - 08	0.4614926	1.20727e - 06	2.98441e - 09
1.3	0.5704380	0.5704374	5.310e - 08	0.5704374	5.83493e - 07	4.59896e - 09
1.4	0.6747519	0.6747518	1.046e - 07	0.6747518	8.83554e - 08	6.24458e - 09
1.5	0.7769433	0.7769434	2.408e - 08	0.7769434	1.10607e - 07	3.39673e - 09
1.6	0.8780836	0.8780838	1.920e - 09	0.8780838	1.53305e - 07	8.10543e - 10
1.7	0.9786840	0.9786842	5.439e - 10	0.9786842	2.41392e - 07	2.02109e - 10
1.8	1.0790020	1.0790024	2.102e - 10	1.0790024	4.03325e - 07	4.94438e - 11
1.9	1.1791710	1.1791715	6.225e - 11	1.1791715	5.22481e - 07	1.20739e - 11
2.0	1.2792610	1.2792616	1.536e - 11	1.2792616	5.71171e - 07	2.97451e - 12

TABLE 1: Error estimate for AFEM and SC Toolbox with Bowman's formula. The accuracy estimate given by SC Toolbox is also consistent with the experiment.

3.7. Example. Let Q be the quadrilateral whose sides are defined by two circular arcs in the upper and lower half plane, perpendicular to the unit circle at the points $e^{i\theta}$, $e^{(\pi-\theta)i}$, $e^{(\theta-\pi)i}$, $e^{-\theta i}$ as well as by the two circular arcs through r, i, -i and -r, i, -i, see Figure 6. If a, b, c, d are the points of intersection of these four circular arcs in the IInd, IIIrd IVth and Ist quadrant respectively, then Q = (Q; a, b, c, d) defines a quadrilateral in the unit disk with $QM(Q; a, b, c, d) = (\pi - 2\beta)/\rho$, where

$$\rho = 2 \log \frac{1+u}{1-u}$$
, $\beta = \arctan \frac{2r}{1-r^2}$, and $u = \tan(\theta/2)$.

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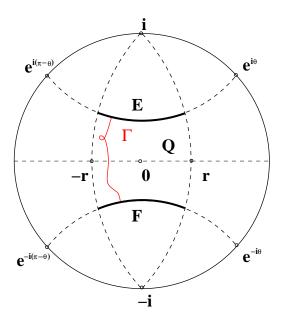


FIGURE 5: The hyperbolic rectangle Q.

θ	AFEM	Exact	Error
0.10	7.592357e + 00	7.597433e + 00	5.076e - 03
0.15	5.056044e + 00	5.054357e + 00	1.687e - 03
0.20	3.784480e + 00	3.779611e + 00	4.869e - 03
0.25	3.010221e + 00	3.012175e + 00	1.954e - 03
0.30	2.497983e + 00	2.498368e + 00	3.849e - 04
0.35	2.130426e + 00	2.129465e + 00	9.616e - 04
1.00	6.207845e - 01	6.206314e - 01	1.531e - 04
1.05	5.753353e - 01	5.754017e - 01	6.645e - 05
1.10	5.335288e - 01	5.330104e - 01	5.185e - 04
1.15	4.931144e - 01	4.929339e - 01	1.805e - 04
1.20	4.546779e - 01	4.546891e - 01	1.114e - 05

Table 2: The modulus of the quadrilateral Q for r=0.4.

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