

```
In[1]:= SetDirectory["~/KappaLib/"];
<< kappaLib-1.2.m
<< helper.m

Loading KappaLib v1.2

Loading helper.m..
```

■ Suppose G^{ijkl} is a symmetric tensor and

$$\{ xi \text{ in } R^4 : \text{gamma}(xi) = 0 \} \supseteq \{ xi \text{ in } R^4 : g(xi,xi) = 0 \}$$

for $\text{gamma}(xi) = G^{ijkl} xi_i xi_j xi_k xi_l$,

$$g = \text{diag}(-1,1,1,1).$$

Claim: There exists a quadratic form h such that

$$\text{gamma} = g(xi,xi) h(xi,xi) \quad \text{for all } xi \text{ in } R^4$$

■ First we define $g = \text{diag}(-1,1,1,1)$ and gamma

```
In[4]:= g = DiagonalMatrix[{-1, 1, 1, 1}];
```

```
In[5]:= symm[i_, j_, k_, l_] := Module[{tmp},
  tmp = Sort[{i, j, k, l}];
  ToExpression[
    "s"
    <> ToString[tmp[[1]]]
    <> ToString[tmp[[2]]]
    <> ToString[tmp[[3]]]
    <> ToString[tmp[[4]]]
  ]
]
```

```
In[6]:= symm[1, 3, 2, 2]
symm[4, 3, 2, 1]
```

```
Out[6]:= s1223
```

```
Out[7]:= s1234
```

```
In[8]:= (* define gamma as above *)
gamma[v_] := Sum[
  symm[i, j, k, l] v[[i]] v[[j]] v[[k]] v[[l]],
  {i, 1, 4},
  {j, 1, 4},
  {k, 1, 4},
  {l, 1, 4}
]
```

(* define quadratic form g *)

$$G[v_] := v.g.v$$

```
In[10]:= gamma[{1, 1, 0, 0}]
G[{1, 1, 0, 0}]
```

```
Out[10]:= s1111 + 4 s1112 + 6 s1122 + 4 s1222 + s2222
```

```
Out[11]:= 0
```

■ Find null vectors for G.

Note: We do not need to trust the below code. We will later check that the vectors are indeed null vectors for G.

```
In[12]:= coordValues = {1, -1, Sqrt[2], -Sqrt[2], Sqrt[3], -Sqrt[3], 0};

LL = Length[coordValues];

nullVectors = {};

For[i0 = 1, i0 ≤ LL, i0++,
  For[i1 = 1, i1 ≤ LL, i1++,
    For[i2 = 1, i2 ≤ LL, i2++,
      For[i3 = 1, i3 ≤ LL, i3++,

        frPoint = {
          coordValues[[i0]],
          coordValues[[i1]],
          coordValues[[i2]],
          coordValues[[i3]]};

        (*frPoint=vars/.frSub;*)

        (* if point is non-zero and belongs
           to the Fresnel surface add it to list. *)
        If[Simplify[frPoint.frPoint] ≠ 0,
          If[Simplify[G[frPoint] = 0],
            nullVectors = Append[nullVectors, frPoint];
          ];
        ];
      ];
    ];
  ];
];
```

In[16]:= nullVectors

```
Out[16]= {{1, 1, 0, 0}, {1, -1, 0, 0}, {1, 0, 1, 0}, {1, 0, -1, 0}, {1, 0, 0, 1}, {1, 0, 0, -1},
{-1, 1, 0, 0}, {-1, -1, 0, 0}, {-1, 0, 1, 0}, {-1, 0, -1, 0}, {-1, 0, 0, 1},
{-1, 0, 0, -1}, {sqrt(2), 1, 1, 0}, {sqrt(2), 1, -1, 0}, {sqrt(2), 1, 0, 1}, {sqrt(2), 1, 0, -1},
{sqrt(2), -1, 1, 0}, {sqrt(2), -1, -1, 0}, {sqrt(2), -1, 0, 1}, {sqrt(2), -1, 0, -1}, {sqrt(2), sqrt(2), 0, 0},
{sqrt(2), -sqrt(2), 0, 0}, {sqrt(2), 0, 1, 1}, {sqrt(2), 0, 1, -1}, {sqrt(2), 0, -1, 1}, {sqrt(2), 0, -1, -1},
{sqrt(2), 0, sqrt(2), 0}, {sqrt(2), 0, -sqrt(2), 0}, {sqrt(2), 0, 0, sqrt(2)}, {sqrt(2), 0, 0, -sqrt(2)},
{-sqrt(2), 1, 1, 0}, {-sqrt(2), 1, -1, 0}, {-sqrt(2), 1, 0, 1}, {-sqrt(2), 1, 0, -1}, {-sqrt(2), -1, 1, 0},
{-sqrt(2), -1, -1, 0}, {-sqrt(2), -1, 0, 1}, {-sqrt(2), -1, 0, -1}, {-sqrt(2), sqrt(2), 0, 0},
{-sqrt(2), -sqrt(2), 0, 0}, {-sqrt(2), 0, 1, 1}, {-sqrt(2), 0, 1, -1}, {-sqrt(2), 0, -1, 1},
{-sqrt(2), 0, -1, -1}, {-sqrt(2), 0, sqrt(2), 0}, {-sqrt(2), 0, -sqrt(2), 0}, {-sqrt(2), 0, 0, sqrt(2)},
{-sqrt(2), 0, 0, -sqrt(2)}, {sqrt(3), 1, 1, 1}, {sqrt(3), 1, 1, -1}, {sqrt(3), 1, -1, 1}, {sqrt(3), 1, -1, -1},
{sqrt(3), 1, sqrt(2), 0}, {sqrt(3), 1, -sqrt(2), 0}, {sqrt(3), 1, 0, sqrt(2)}, {sqrt(3), 1, 0, -sqrt(2)},
{sqrt(3), -1, 1, 1}, {sqrt(3), -1, 1, -1}, {sqrt(3), -1, -1, 1}, {sqrt(3), -1, -1, -1},
{sqrt(3), -1, sqrt(2), 0}, {sqrt(3), -1, -sqrt(2), 0}, {sqrt(3), -1, 0, sqrt(2)}, {sqrt(3), -1, 0, -sqrt(2)},
{sqrt(3), sqrt(2), 1, 0}, {sqrt(3), sqrt(2), -1, 0}, {sqrt(3), sqrt(2), 0, 1}, {sqrt(3), sqrt(2), 0, -1},
{sqrt(3), -sqrt(2), 1, 0}, {sqrt(3), -sqrt(2), -1, 0}, {sqrt(3), -sqrt(2), 0, 1}, {sqrt(3), -sqrt(2), 0, -1},
{sqrt(3), sqrt(3), 0, 0}, {sqrt(3), -sqrt(3), 0, 0}, {sqrt(3), 0, 1, sqrt(2)}, {sqrt(3), 0, 1, -sqrt(2)},
{sqrt(3), 0, -1, sqrt(2)}, {sqrt(3), 0, -1, -sqrt(2)}, {sqrt(3), 0, sqrt(2), 1}, {sqrt(3), 0, sqrt(2), -1},
{sqrt(3), 0, -sqrt(2), 1}, {sqrt(3), 0, -sqrt(2), -1}, {sqrt(3), 0, sqrt(3), 0}, {sqrt(3), 0, -sqrt(3), 0},
{sqrt(3), 0, 0, sqrt(3)}, {sqrt(3), 0, 0, -sqrt(3)}, {-sqrt(3), 1, 1, 1}, {-sqrt(3), 1, 1, -1},
{-sqrt(3), 1, -1, 1}, {-sqrt(3), 1, -1, -1}, {-sqrt(3), 1, sqrt(2), 0}, {-sqrt(3), 1, -sqrt(2), 0},
{-sqrt(3), 1, 0, sqrt(2)}, {-sqrt(3), 1, 0, -sqrt(2)}, {-sqrt(3), -1, 1, 1}, {-sqrt(3), -1, 1, -1},
{-sqrt(3), -1, -1, 1}, {-sqrt(3), -1, -1, -1}, {-sqrt(3), -1, sqrt(2), 0}, {-sqrt(3), -1, -sqrt(2), 0},
{-sqrt(3), -1, 0, sqrt(2)}, {-sqrt(3), -1, 0, -sqrt(2)}, {-sqrt(3), sqrt(2), 1, 0}, {-sqrt(3), sqrt(2), -1, 0},
{-sqrt(3), sqrt(2), 0, 1}, {-sqrt(3), sqrt(2), 0, -1}, {-sqrt(3), -sqrt(2), 1, 0}, {-sqrt(3), -sqrt(2), -1, 0},
{-sqrt(3), -sqrt(2), 0, 1}, {-sqrt(3), -sqrt(2), 0, -1}, {-sqrt(3), sqrt(3), 0, 0}, {-sqrt(3), -sqrt(3), 0, 0},
{-sqrt(3), 0, 1, sqrt(2)}, {-sqrt(3), 0, 1, -sqrt(2)}, {-sqrt(3), 0, -1, sqrt(2)}, {-sqrt(3), 0, -1, -sqrt(2)},
{-sqrt(3), 0, sqrt(2), 1}, {-sqrt(3), 0, sqrt(2), -1}, {-sqrt(3), 0, -sqrt(2), 1}, {-sqrt(3), 0, -sqrt(2), -1},
{-sqrt(3), 0, sqrt(3), 0}, {-sqrt(3), 0, -sqrt(3), 0}, {-sqrt(3), 0, 0, sqrt(3)}, {-sqrt(3), 0, 0, -sqrt(3)}}}
```

■ We found 124 null vectors for g. We can think of these as a discretisation of the null cone.

In[17]:= Length[nullVectors]

Out[17]= 124

■ Verify that all vectors are indeed null vectors

```
In[18]:= Union[Table[
  G[nullVectors[[i]]],
  {i, 1, Length[nullVectors]}
]]
```

Out[18]= {0}

■ Since these vectors are null for g , they are null for γ

```
In[19]:= eqs = Table[
  gamma[nullVectors[[i]],
    {i, 1, Length[nullVectors]}
];
```

```
In[20]:= show[simp[eqs]]
```

Out[20]/MatrixForm=

```
1 :
2 :
3 :
4 :
5 :
6 :
7 :
8 :
9 :
10 :
11 :
12 :
13 :
14 :
15 :
16 :
17 :
18 :
19 :
20 :
21 :
22 :
23 :
24 :
25 :
26 :
27 :
28 :
29 :
30 :
31 :
32 :
33 :
34 :
35 :
36 :
37 :
38 :
39 :
40 :
41 :
42 :
43 :
```

```

44 :
45 :
46 :
47 :
48 :
49 :
50 :
51 :
52 :
53 :
54 :
55 : 9 s1111 + 12 √3 s1112 + 12 √3 s1113 - 12 √3 s1114 + 18 s1122 + 36 s1123 - 36 s1124 + 18 s11
56 : 9 s1111 - 12 √3 s1112 - 12 √3 s1113 + 12 √3 s1114 + 18 s1122 + 36 s1123 - 36 s1124 + 18 s11
57 : 9 s1111 - 12 √3 s1112 + 12 √3 s1113 - 12 √3 s1114 + 18 s1122 - 36 s1123 + 36 s1124 + 18 s11
58 : 9 s1111 + 12 √3 s1112 - 12 √3 s1113 + 12 √3 s1114 + 18 s1122 - 36 s1123 + 36 s1124 + 18 s11
59 : 9 s1111 + 12 √3 s1112 - 12 √3 s1113 - 12 √3 s1114 + 18 s1122 - 36 s1123 - 36 s1124 + 18 s11
60 : 9 s1111 - 12 √3 s1112 + 12 √3 s1113 + 12 √3 s1114 + 18 s1122 - 36 s1123 - 36 s1124 + 18 s11
61 : 9 s1111 - 12 √3 s1112 - 12 √3 s1113 - 12 √3 s1114 + 18 s1122 + 36 s1123 + 36 s1124 + 18 s11
62 : 9 s1111 + 12 √3 s1112 + 12 √3 s1113 + 12 √3 s1114 + 18 s1122 + 36 s1123 + 36 s1124 + 18 s11

```

■ We now have 62 linear equations constraining the coefficients in gamma.

```
In[21]:= sol = Solve[toEqs[eqs], Variables[eqs]]
```

Solve::svars : Equations may not give solutions for all "solve" variables. >>

```

Out[21]= { { s1222 -> -s1112, s1223 -> -s1113/3, s1224 -> -s1114/3,
s1233 -> -s1112/3, s1234 -> 0, s1244 -> -s1112/3, s1333 -> -s1113, s1334 -> -s1114/3,
s1344 -> -s1113/3, s1444 -> -s1114, s2222 -> -s1111 - 6 s1122, s2223 -> -3 s1123,
s2224 -> -3 s1124, s2233 -> -s1111/3 - s1122 - s1133, s2234 -> -s1134,
s2244 -> -s1111/3 - s1122 - s1144, s2333 -> -3 s1123, s2334 -> -s1124,
s2344 -> -s1123, s2444 -> -3 s1124, s3333 -> -s1111 - 6 s1133, s3334 -> -3 s1134,
s3344 -> -s1111/3 - s1133 - s1144, s3444 -> -3 s1134, s4444 -> -s1111 - 6 s1144 } }

```

```
In[22]:= Length[sol]
```

```
Out[22]= 1
```

```
In[23]:= vars = {x0, x1, x2, x3};
```

```
In[24]:= gammaConstrained = FullSimplify[gamma[vars] //. sol[[1]]]
```

```

Out[24]= (x0^2 - x1^2 - x2^2 - x3^2) (s1111 (x0^2 + x1^2 + x2^2 + x3^2) +
2 (2 s1112 x0 x1 + 3 s1122 x1^2 + x2 (2 s1113 x0 + 6 s1123 x1 + 3 s1133 x2) +
2 (s1114 x0 + 3 s1124 x1 + 3 s1134 x2) x3 + 3 s1144 x3^2))

```

```

In[25]:= HH = - (
( s1111      2 s1112      2 s1113      2 s1114
2 s1112  s1111 + 6 s1122      6 s1123      6 s1124
2 s1113      6 s1123      s1111 + 6 s1133      6 s1134
2 s1114      6 s1124      6 s1134      s1111 + 6 s1144 )
);

```

```
In[26]:= f1 = G[vars]  
f2 = Simplify[vars.HH.vars]
```

```
Out[26]=  $-x_0^2 + x_1^2 + x_2^2 + x_3^2$ 
```

```
Out[27]=  $-s_{1111} (x_0^2 + x_1^2 + x_2^2 + x_3^2) -$   
 $2 (2 s_{1112} x_0 x_1 + 3 s_{1122} x_1^2 + 2 s_{1113} x_0 x_2 + 6 s_{1123} x_1 x_2 + 3 s_{1133} x_2^2 +$   
 $2 s_{1114} x_0 x_3 + 6 s_{1124} x_1 x_3 + 6 s_{1134} x_2 x_3 + 3 s_{1144} x_3^2)$ 
```

```
In[28]:= Simplify[gammaConstrained - f1 f2]
```

```
Out[28]= 0
```

- For a similar argument for two Lorentz metrics, see: Richard A. Toupin, Elasticity and electromagnetics, in: *Non-Linear Continuum Theories*, C.I.M.E. Conference, Bressanone, Italy 1965. C. Truesdell and G. Grioli coordinators. Pp.203-342.