

■ Lemma 4.3: Computations for Claim 1, Case C

```
In[1]:= SetDirectory["~/writing/WIP/KappaLib/"];
<< KappaLib.m

KappaLib v1.1

In[3]:= Ax = DiagonalMatrix[{a1, 0, 0}];
Bx = emGeneralSymmetric3x3["B"];
Cx = emGeneral3x3["C"];
Dx = Transpose[Cx];

In[7]:= eq1 = Flatten[Cx.Cx + Ax.Bx + IdentityMatrix[3]];
eq2 = Flatten[Bx.Cx + Transpose[Cx].Bx];
eq3 = Flatten[Cx.Ax + Ax.Transpose[Cx]];
eqs = Join[Join[eq1, eq2], eq3];

In[11]:= Simplify[Union[eqs]] // MatrixForm
```

Out[11]//MatrixForm=

$$\left\{ \begin{array}{l} 0 \\ 2 a1 C11 \\ a1 C21 \\ a1 C31 \\ 2 (B11 C11 + B12 C21 + B13 C31) \\ 1 + a1 B11 + C11^2 + C12 C21 + C13 C31 \\ C11 C21 + C21 C22 + C23 C31 \\ B11 C12 + B22 C21 + B12 (C11 + C22) + B23 C31 + B13 C32 \\ 2 (B12 C12 + B22 C22 + B23 C32) \\ a1 B12 + C11 C12 + C12 C22 + C13 C32 \\ 1 + C12 C21 + C22^2 + C23 C32 \\ B11 C13 + B23 C21 + B12 C23 + B33 C31 + B13 (C11 + C33) \\ B13 C12 + B12 C13 + B23 C22 + B22 C23 + B33 C32 + B23 C33 \\ 2 (B13 C13 + B23 C23 + B33 C33) \\ a1 B13 + C11 C13 + C12 C23 + C13 C33 \\ C13 C21 + C23 (C22 + C33) \\ C11 C31 + C21 C32 + C31 C33 \\ C12 C31 + C32 (C22 + C33) \\ 1 + C13 C31 + C23 C32 + C33^2 \end{array} \right\}$$

■ Since  $a1 \neq 0$ , it follows that  $C11, C21, C31 = 0$ .

```
In[12]:= subs = {};
subs = Append[subs, C11 -> 0];
subs = Append[subs, C21 -> 0];
subs = Append[subs, C31 -> 0]; Simplify[Union[eqs /. subs]] // MatrixForm
```

Out[15]//MatrixForm=

$$\left\{ \begin{array}{l} 0 \\ 1 + a1 B11 \\ B11 C12 + B12 C22 + B13 C32 \\ 2 (B12 C12 + B22 C22 + B23 C32) \\ a1 B12 + C12 C22 + C13 C32 \\ 1 + C22^2 + C23 C32 \\ B11 C13 + B12 C23 + B13 C33 \\ B13 C12 + B12 C13 + B23 C22 + B22 C23 + B33 C32 + B23 C33 \\ 2 (B13 C13 + B23 C23 + B33 C33) \\ a1 B13 + C12 C23 + C13 C33 \\ C23 (C22 + C33) \\ C32 (C22 + C33) \\ 1 + C23 C32 + C33^2 \end{array} \right\}$$

- Equation  $a_1 B_{11} = 0$  implies that  $B_{11} \neq 0$
- Equation  $C_{23} C_{32} + C_{33}^2 = 0$  implies that  $C_{23} \neq 0$  and  $C_{32} \neq 0$

- Coordinate transformation

```
In[16]:= kappa = emABCDToKappa[Ax, Bx, Cx, Dx];
kappaSub = kappa //. subs;
emKappaToMatrix[kappaSub] // MatrixForm
```

Out[18]/MatrixForm=

$$\begin{pmatrix} 0 & 0 & 0 & B_{11} & B_{12} & B_{13} \\ C_{12} & C_{22} & C_{32} & B_{12} & B_{22} & B_{23} \\ C_{13} & C_{23} & C_{33} & B_{13} & B_{23} & B_{33} \\ a_1 & 0 & 0 & 0 & C_{12} & C_{13} \\ 0 & 0 & 0 & 0 & C_{22} & C_{23} \\ 0 & 0 & 0 & 0 & C_{32} & C_{33} \end{pmatrix}$$

- Define Jacobian matrix for coordinate transformation

$\tilde{x}^0 = x^0 + x^3$   
 $\tilde{x}^i = x^i, i=1,2,3.$

See `emCoordinateChange` in `KappaLib` source code.

```
In[19]:= L = {
  {1, 0, 0, 1},
  {0, 1, 0, 0},
  {0, 0, 1, 0},
  {0, 0, 0, 1}
};

kappaTrans = emCoordinateChange[kappaSub, L];
{Atrans, Btrans, Ctrans, Dtrans} = emKappaToABCD[kappaTrans];
Simplify[Atrans] // MatrixForm
Simplify[Det[Atrans]]
```

Out[22]/MatrixForm=

$$\begin{pmatrix} a_1 + B_{22} + 2C_{12} & -B_{12} + C_{22} & C_{32} \\ -B_{12} + C_{22} & B_{11} & 0 \\ C_{32} & 0 & 0 \end{pmatrix}$$

Out[23]=  $-B_{11} C_{32}^2$